Ross Ogilvie

30th September, 2024

## 13. Is this an applied math course?

In economics, the Black-Scholes equation is a PDE that describes the price V of an (Europeanstyle) option under some assumptions about the risk and expected return, as a function of time t and current stock price S. The equation is

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} = rV - rS \frac{\partial V}{\partial S},$$

where r and  $\sigma$  are constants representing the interest rate and the stock volatility respectively. Describe the order of this equation, and whether it is elliptic, parabolic, and/or hyperbolic.

(3 points)

## 14. Around and around

Consider the unit circle  $C = \{x^2 + y^2 = 1\} \subset \mathbb{R}^2$ . In this question we will evaluate the integral

$$\int_C y \, d\sigma \tag{(*)}$$

in two different ways, demonstrating that it does not depend on the choice of parametrisation.

(a) Consider a regular parameterisation  $\Phi$  of a subset A and a continuous function f on A. Why (or under what conditions) is the integral unchanged by removing a point from A: (1 bonus point)

$$\int_A f \, d\sigma = \int_{A \setminus \{a\}} f \, d\sigma.$$

Therefore in order to compute the submanifold integration (\*) it is enough to use parameterisation that cover all but finitely many points of C.

- (b) Consider the regular parametrisation  $\Phi: (0, 2\pi) \to C$  given by  $t \mapsto (\cos t, \sin t)$ . Compute the integral (\*) using this parametrisation. (2 points)
- (c) Consider upper and lower halves of the circle:  $U_1 = \{(x, y) \in C \mid y > 0\}$  and  $U_2 = \{(x, y) \in C \mid y > 0\}$  $C \mid y < 0$ . There are obvious parametrisations  $\Phi_i : (-1,1) \rightarrow U_i$  given by  $\Phi_1(x) =$  $(x, +\sqrt{1-x^2})$  and  $\Phi_2(x) = (x, -\sqrt{1-x^2})$ . Compute (\*) using these parametrisations.

(2 points)

(2 points) (d) Compute this integral using the divergence theorem.

## 15. The Proof is Left as an Exercise for the Reader

Using Definitions 2.4 and 2.7, prove Lemma 2.9: The following properties hold for  $a, b \in \mathbb{R}$  and  $f, g \in C(A).$ 

- (i) Linearity:  $\int_A af + bg \, d\sigma = a \int_A f \, d\sigma + b \int_A g \, d\sigma$ . (1 point)
- (ii) Order Preserving: if  $f \leq g$  on A then  $\int_A f \, d\sigma \leq \int_A g \, d\sigma$ . (1 point)
- (iii) Triangle Inequality:  $\left|\int_A f \, d\sigma\right| \leq \int_A |f| \, d\sigma$ . (1 point)

(iv) Transformation: If  $P : \mathbb{R}^n \to \mathbb{R}^n$  is a euclidean motion (translation, reflection, rotation) and  $s \in \mathbb{R}^+$  is a scaling factor then  $\int_A f \, d\sigma = s^k \int_{(sP)^{-1}[A]} f \circ (sP) \, d\sigma$ . (3 points)

# 16. The Black Spot

Consider the plane  $\mathbb{R}^2$ , a disc  $B_r = \{x^2 + y^2 \le r^2\}$  and the function  $g(x, y) = \ln(x^2 + y^2)$ .

(a) By calculating  $\nabla g \cdot N$  for the outward pointing normal  $N = \frac{1}{r}(x, y)$ , show that the value of the integral

$$\int_{\partial B_r} \nabla g \cdot N \, d\sigma$$

does not depend on the radius r.

(b) Can you explain this fact using the divergence theorem? Hint: Apply the divergence theorem to the region  $A_{r,R} = B_R \setminus \overline{B_r}$  for two different radii r < R. (3 points)

(2 points)