# Analysis III

#### 2. Exercise: Charts

## **Preparation Exercises**

- **8. Properties of charts.** Let X be a manifold with atlas A. Let  $\phi: U \to \phi[U] \subset \mathbb{R}^n$  be a chart of A.
  - (a) State the definition of a chart and what it means for two charts to be compatible.
  - (b) Is compatibility of charts an equivalence relation?
  - (c) Restriction: If V is an open subset of U, prove  $\psi := \phi|_V : V \to \mathbb{R}^n$  is a chart of X that is compatible with  $\phi$ .
  - (d) Composition: If  $F : \phi[U] \to W \subset \mathbb{R}^n$  is a diffeomorphism, prove  $\psi := F \circ \phi : U \to W$  is a chart of X that is compatible with  $\phi$ .
  - (e) Show that every point  $x \in X$  has a neighbourhood V such that there is a chart  $\psi: V \to B(0,1) \subset \mathbb{R}^n$  with  $\psi(x) = 0$  that is compatible with A.

#### 9. Graphs as manifolds.

Consider the parabola  $X = \{(x_1, x_2) \in \mathbb{R}^2 \mid x_2 = x_1^2\}$  as a topological space, with the subspace topology from  $\mathbb{R}^2$ . In this question we will give it a manifold structure. This means, we give it an atlas. This example falls within Beispiel 1.18(iv) of the script, but try to prove it by hand.

Let  $\Pi_1(x_1, x_2) = x_1, \Pi_2(x_1, x_2) = x_2$  be the projections  $\mathbb{R}^2 \to \mathbb{R}$  onto the coordinate axes.

- (a) How do we know that X is Hausdorff and Lindelöf?
- (b) Let  $\phi_1 := \Pi_1|_X$ . Is this a chart for X?
- (c) Is  $\mathcal{A} := \{\phi_1\}$  an atlas for X?
- (d) Let  $U_2 := X \cap \{x_1 > 0\}$  and  $\phi_2 := \Pi_2|_{U_2}$ . Prove  $\phi_2$  is a chart that is compatible with  $\mathcal{A}$ .

#### In Class Exercises

#### 10. Open subsets of a manifold.

Let  $Y \subset X$  be an open subset of the manifold X with atlas  $\mathcal{A}$ . Give Y a manifold structure.

## 11. The tangent space is a vector space.

Let M be an n-dimensional manifold. Prove, that for all  $x \in M$  the tangent space  $T_xM$  is a vector space.

#### 12. Stereographic projection is compatible with regular projection.

Consider the sphere from Example 1.18(iii) in the lecture script. We take n=1 to get the circle  $\mathbb{S}^1=\{x_0^2+x_1^2=1\}$ . We defined two charts  $\phi_N:\mathbb{S}^1\setminus\{e_0\}\to\mathbb{R}$  and  $\phi_S:\mathbb{S}^1\setminus\{-e_0\}\to\mathbb{R}$ , showed they were compatible, and that they form an atlas  $\mathcal{A}_{\text{stereo}}$ .

On the other hand, we can use the usual projections to get charts for  $\mathbb{S}^1$ . Let

$$\phi_1 := \Pi_0|_{\mathbb{S}^1 \cap \{x_1 > 0\}}, \ \phi_2 := \Pi_0|_{\mathbb{S}^1 \cap \{x_1 < 0\}}, \ \phi_3 := \Pi_1|_{\mathbb{S}^1 \cap \{x_0 > 0\}}, \ \phi_4 := \Pi_1|_{\mathbb{S}^1 \cap \{x_0 < 0\}},$$

(a) Write out the vector formulae from the script in the case n=1 in coordinates to get

$$\phi_N(x_0, x_1) = \frac{x_1}{1 - x_0}, \qquad \phi_S(x_0, x_1) = \frac{x_1}{1 + x_0}$$

$$\phi_N^{-1}(y) = \left(\frac{\|y\|^2 - 1}{\|y\|^2 + 1}, \frac{2y}{\|y\|^2 + 1}\right), \qquad \phi_S^{-1}(y) = \left(-\frac{\|y\|^2 - 1}{\|y\|^2 + 1}, \frac{2y}{\|y\|^2 + 1}\right).$$

- (b) Show that  $\phi_1$  is a chart of  $\mathbb{S}^1$ .
- (c) Show that  $\phi_3$  is compatible with  $\phi_1$ .
- (d) Is  $\phi_2$  compatible with  $\phi_1$ ?
- (e) Show that  $\phi_1$  is compatible with  $\phi_S$ .

#### 13. The manifold $\mathbb{R}/\mathbb{Z}$ .

Recall from Exercise 6 the quotient space  $\mathbb{R}/\mathbb{Z}$  and the quotient map  $p: \mathbb{R} \to \mathbb{R}/\mathbb{Z}$ . In particular we saw for every open unit interval  $I_x = (x - 0.5, x + 0.5)$  that  $p|_{I_x}$  is a homeomorphism. For any  $x \in \mathbb{R}$ , let  $U_x := p[I_x]$  and  $\phi_x := (p|_{I_x})^{-1}: U_x \to I_x$ .

- (a) Is  $\phi_x$  a chart of  $\mathbb{R}/\mathbb{Z}$ ?
- (b) Prove that  $\phi_x$  and  $\phi_{x+n}$  are compatible, where  $n \in \mathbb{Z}$ .
- (c) Prove that  $\phi_x$  and  $\phi_y$  are compatible, for any  $x, y \in \mathbb{R}$ .
- (d) Why is  $\{\phi_x|x\in\mathbb{R}\}$  an atlas for  $\mathbb{R}/\mathbb{Z}$ .

#### **Additional Exercises**

## 14. Non-compatible differentiable atlases.

Let  $\mathcal{A}$  be the natural atlas of  $\mathbb{R}$ , namely  $\mathcal{A} = \{id_{\mathbb{R}}\}$ . Find another atlas  $\widetilde{\mathcal{A}}$  of  $\mathbb{R}$  that is not compatible with  $\mathcal{A}$ . (Compare to Exercise 1.20 in the script.)

[Hint. It is possible to find such an atlas  $\widetilde{\mathcal{A}}=\{f\}$  that contains only one chart.]

## Terminology

Definitionsbreich = domain.

dicht = dense.

Karte = chart.

Umkehrabbildung = inverse map.

verträglich = compatible.