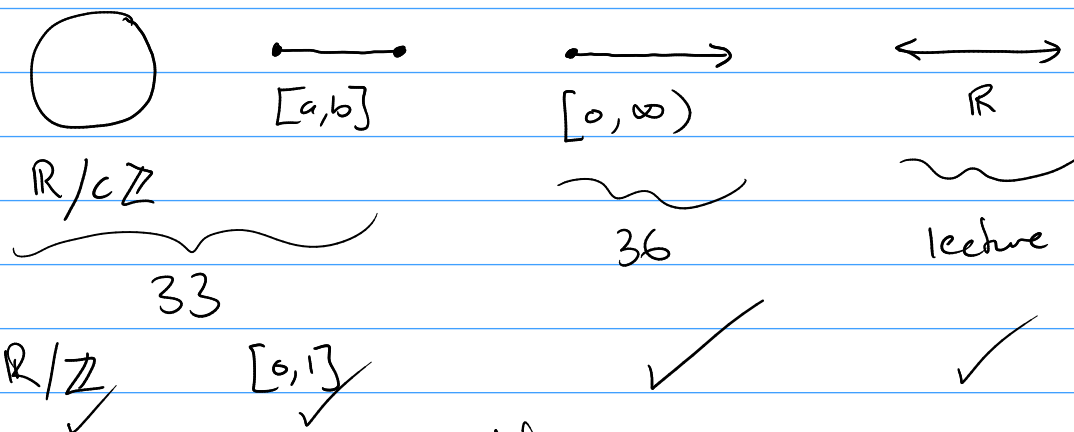


Tutorial 11

All closed 1-dimensional manifolds (with boundary)



33. one method

write down a complete system
of eigenfunctions

$$H_{[0,b]}(x,y,t) \quad [0,b] \rightarrow [0,1]$$

$$x \mapsto \frac{1}{b}x$$

$$\Phi(x,t) = \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{x^2}{4t}\right)$$

$$\frac{1}{b} \Phi\left(\frac{1}{b}x, \frac{1}{b^2}t\right) = \frac{1}{b} \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{x^2}{4t}\right) = \Phi(x,t)$$

$$H_{[0,b]}(x,y,t) = \frac{1}{b} H_{[0,1]}(\frac{1}{b}x, \frac{1}{b}y, \frac{1}{b^2}t)$$

$$H_{[0,b]} - \Phi(x-y,t) = \frac{1}{b} H_{[0,1]}(\frac{1}{b}x, \frac{1}{b}y, \frac{1}{b^2}t) - \frac{1}{b} \Phi(\frac{1}{b}(x-y), \frac{1}{b^2}t)$$

$$= \frac{1}{b} \{ H_{[0,1]}(x', y', t') - \Phi(x'-y', t') \}$$

has (ii)

$$H_{[a,b]}(x,y,t) := H_{[0,b-a]}(x-a, y-a, t)$$

$$H_{[a,b]}(x,y,t) - \Phi(x-y,t) = H_{[a,b]}(x,y,t) - \Phi((x-a)-(y-a),t)$$

$$\text{Ex. a) } u \in C^2(\overline{\Omega} \times (0, \infty)) \quad \Omega = (0, \infty) \\ u(0, t) = 0$$

$$\tilde{u} = \begin{cases} u & x > 0 \\ -u(-x, t) & x < 0 \\ 0 & x = 0 \end{cases} \quad \text{clearly also } C^2$$

$$\text{Well it's ds.} \quad \lim_{x \rightarrow 0^-} \tilde{u}(x, t) = \lim_{x \rightarrow 0^-} -u(-x, t) = -\lim_{y \rightarrow 0^+} u(y, t) = 0 \quad x = -y$$

$$(\partial_t u)(0, t) = \lim_{h \rightarrow 0} \frac{u(0, t+h) - u(0, t)}{h} = \lim_{h \rightarrow 0} \frac{0-0}{h} = 0$$

$$\partial_t u \in C^1(\overline{\Omega} \times (0, \infty))$$

$$\partial_t \tilde{u} = \begin{cases} \partial_t u & x > 0 \\ -\partial_t u(-x, t) & x < 0 \\ 0 & x = 0 \end{cases}$$

$\partial_t \tilde{u}$ same argument.

$$\partial_x(-u(-x, t)) = (\partial_x u)(-x, t)$$

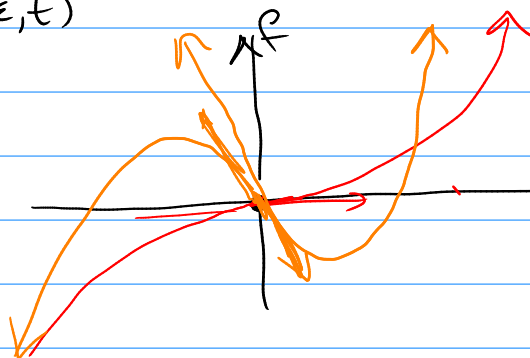
X-derivative

$$\partial_x \tilde{u} = \begin{cases} \partial_x u(x, t) & x > 0 \\ \partial_x u(-x, t) & x < 0 \\ \lim_{\varepsilon \rightarrow 0} \partial_x u(\varepsilon, t) & x = 0 \end{cases}$$

$$\partial_x u \in C^1(\overline{\Omega} \times (0, \infty)) \\ \Rightarrow \text{extends continuously to } x=0$$

Also

$\partial_x \partial_t \tilde{u}$ is ds on \mathbb{R}



$$u(x) = x^2 - x = x(x-1)$$

$$u'(x) = 2x - 1$$

$$u'' = 2$$

$$\tilde{u} = -x^2 - x \quad \text{for } x < 0$$

$$\partial_x \tilde{u} = -2x - 1$$

$$\partial_{xx} \tilde{u} = -2$$

Only need to check $\partial_{xx} \tilde{u}$

$$\partial_{xx} u \text{ is ds as } x \rightarrow 0^+$$

$$\partial_{xx} u = \partial_t u \quad \text{on } x \neq 0 \\ \uparrow \text{ ds on } \mathbb{R}$$

$y' = y$ if we show y is cts. and diff'ble
 $\Rightarrow y$ is C^1
 $\Rightarrow y$ is C^2
 \vdots
 $\Rightarrow y$ is C^∞

c) If u is a solⁿ to HE on $[0, \infty)$ we know by
 (b) \tilde{u} is a solⁿ on \mathbb{R} .
 and
 $|\tilde{u}|$ is bounded

So maximum principle applies $|\tilde{u}|$ is bounded by $\sup |\tilde{h}|$
 $= \sup |h|$

$$\begin{aligned}
 d) \quad \tilde{u} &= \int_{-\infty}^{\infty} \Phi(x-y, t) \tilde{h}(y) dy \\
 &= \int_{-\infty}^0 " (-h(-y)) dy + \int_0^{\infty} " \\
 &= \text{end result.} \quad \int_0^{\infty} \left(\text{find a sol}^n + \text{coord trans for find sol}^n \right) h(y) dy.
 \end{aligned}$$

Harmonic half plane $u(x, y) = \Phi(x-y) - \Phi(x-R(y))$

$$34. \quad \frac{1}{7} \frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = 0$$

$$\tau = 7t$$

$$\frac{\partial u}{\partial \tau} - \frac{\partial^2 u}{\partial x^2} = 0$$

35. $\dot{u} - \partial_{xx} u = 0 \quad \Omega = [0, \pi]$

$u(0, t) = u(\pi, t) = 0 = g$

$u(x, 0) = h(x) = x^2(\pi - x)$

$$u(x, t) = \int_0^\pi H_{[0, \pi]}(x, y, t) h(y) dy.$$

$$= \int_0^\pi \frac{1}{\pi} H_{[0, \pi]}(\frac{1}{\pi}x, \frac{1}{\pi}y, \frac{1}{\pi^2}t) h(y) dy$$

$$= \int_0^\pi \frac{2}{\pi} \sum_{k=1}^{\infty} e^{-k^2 t} \sin(kx) \sin(ky) h(y) dy$$

$$= \frac{2}{\pi} \sum e^{-k^2 t} \underbrace{\sin(kx)}_{\text{eigenfunktion}} \underbrace{\int_0^\pi \sin(ky) y^2(\pi - y) dy}_{a_k}$$

$$= -2\pi k^{-3} (1 + 2 \cos k\pi)$$

$$= 4 \sum_{k \text{ odd}} k^{-3} e^{-k^2 t} \sin(kx)$$

$$- 12 \sum_{k \text{ even}} k^{-3} e^{-k^2 t} \sin(kx)$$

± 1
 $\swarrow \quad \searrow$
 $k \text{ odd} \quad k \text{ even}$
 $\quad \quad \quad \downarrow \quad \downarrow$
 $\quad \quad \quad -1 \quad 3.$

