

## 6. Linear Partial Differential Equations

- (a) Let  $b : \mathbb{R}^n \rightarrow \mathbb{R}^n$  and  $c : \mathbb{R}^n \rightarrow \mathbb{R}$  be continuously differentiable functions. Then, let  $x : I \rightarrow \mathbb{R}^n$  be a solution of the ordinary differential equation

$$\dot{x}(s) = b(x(s))$$

and  $u : \mathbb{R}^n \rightarrow \mathbb{R}$  be a solution of the homogeneous, linear partial differential equation

$$b(x) \cdot \nabla u(x) + c(x)u(x) = 0.$$

Show that the function  $z(s) := u(x(s))$  is a solution of the ordinary differential equation

$$\dot{z}(s) = -c(x(s))z(s).$$

(2 point(s))

- (b) Consider a PDE of the form  $F(\nabla u(x), u(x), x) = 0$ . Suppose that  $F$  is linear in the derivatives and has continuously differentiable coefficients. That is, it can be written in the form

$$F(p, z, x) = b(z, x) \cdot p + c(z, x)$$

with  $b$  and  $c$  continuously differentiable. Show that the characteristic curves  $(x(s), z(s))$  for  $z(s) := u(x(s))$  can be described by ODEs that are independent of  $p(s) := \nabla u(x(s))$ .

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(4 point(s))

- (c) With the help of the previous part, re-derive the solution of the inhomogeneous transport equation.

(2 point(s))

### Solution.

- (a) By computation

$$\frac{d}{ds} z(s) = \nabla u(x(s)) \cdot \dot{x}(s) = \nabla u(x(s)) \cdot b(x(s)) = -c(x(s))u(x(s)) = -c(x(s))z(s).$$

- (b) We follow the working at the beginning of Section 1.5 of the lecture script, specialising the argument to this particular case. As there, we have

$$\frac{dp}{ds} = \text{Hess}(u)\dot{x} = \left( \sum_j \partial_i \partial_j u \dot{x}_j \right),$$

where  $\text{Hess}(u)$  is the matrix of second derivatives of  $u$ . The total derivative of  $F$  with respect to  $x$  is

$$\begin{aligned} 0 &= \partial_p F \cdot \partial_i p + \partial_z F \partial_i z + \partial_i F \\ &= b \cdot \partial_i p + \partial_z F p_i + \partial_i F \\ 0 &= \text{Hess}(u)b + \partial_z F p + \nabla F. \end{aligned}$$

If we suppose that the characteristic has the property that  $\dot{x} = b(z, x)$ , then

$$\dot{p} = -\partial_z F p - \nabla F.$$

So  $p(s)$  is described by an ODE and the assumption about  $\dot{x}$  does not involve  $p$ . Finally,

$$\dot{z} = \nabla u \cdot \dot{x} = p \cdot \dot{x} = p \cdot b = -c(z, x)$$

since by assumption  $F(p(s), z(s), x(s)) = 0$ . This also does not depend on  $p$ . Hence we have the ODE for the characteristics, and the  $\dot{x}$  and  $\dot{z}$  equations do not depend on  $p$ .

(c) The inhomogeneous transport equation is defined by

$$F(p, z, x) = \tilde{b} \cdot p - f(\tilde{x})$$

where  $\tilde{x} = (x, t)$  and  $\tilde{b} = (b, 1)$  in  $\mathbb{R}^{n+1}$ . From the equations we have just derived, we see that  $\dot{\tilde{x}}(s) = (b, 1)$  tells us that the characteristic lines are straight lines  $\tilde{x}(s) = (bs + x_0, s)$ . Or in non-parametric form  $x = bt + x_0$ . The next ODE is  $\dot{z}(s) = f(x(s), s) = f(x_0 + bs, s)$ . This too can be directly integrated now

$$z(t) - z(0) = \int_0^t \dot{z}(s) ds = \int_0^t f(x_0 + bs, s) ds = \int_0^t f(x - bt + bs, s) ds.$$

Together with the initial condition  $z(0) = u(x(0), 0) = u(x_0, 0) = g(x - bt)$  this is exactly the solution that we found previously.

**7. Solving PDEs** Solve the initial value problems of the following PDEs using the method of characteristics. You may assume that  $g$  is continuously differentiable on the corresponding domain.

(a)  $x_1 \partial_1 u + x_2 \partial_2 u = 2u$  on the domain  $x_1 \in \mathbb{R}, x_2 > 0$ , with initial condition  $u(x_1, 1) = g(x_1)$ .  
(4 point(s))

(b)  $x_1 \partial_2 u - x_2 \partial_1 u = u$  on the domain  $x_1, x_2 > 0$ , with initial condition  $u(x_1, 0) = g(x_1)$ .  
(4 point(s))

(c)  $x_1 \partial_1 u + 2x_2 \partial_2 u + \partial_3 u = 3u$  on  $x_1, x_2 \in \mathbb{R}, x_3 > 0$ , with initial condition  $u(x_1, x_2, 0) = g(x_1, x_2)$ .  
(4 point(s))

(d)  $u \partial_1 u + \partial_2 u = 1$  on the domain  $x_1, x_2 > 0$ , with initial condition  $u(x_1, x_1) = \frac{1}{2}x_1$ .  
(5 point(s))

**Solution.** These PDEs are all of the linear type of the previous question, so we can use the ODEs for the characteristics that we have already derived.

- (a) Write the PDE as  $(x_1, x_2) \cdot p - 2z = 0$ . The the ODE for  $\dot{x}$  is  $\dot{x}_i(s) = x_i$ , which is solved by the exponential  $x(s) = e^s(a, 1)$ . These are the characteristics. Likewise  $\dot{z} = 2z$  gives  $z(s) = e^{2s}z(0) = e^{2s}u(a, 1)$ , which tells us the value of  $u$  on those lines. Now we must apply the initial condition. Given a point  $(x_1, x_2)$  it must lie on the same characteristic as  $(x_1/x_2, 1)$ , which is easy to see if you rescale the parameter  $r = e^s > 0$ . Then

$$\begin{aligned} u(e^s(a, 1)) &= u(x(s)) = z(s) = e^{2s}u(a, 1) \\ u(x_1, x_2) &= u(x_2(x_1/x_2, 1)) = (x_2)^2 u(x_1/x_2, 1) = x_2^2 g(x_1/x_2). \end{aligned}$$

- (b) This PDE is  $(-x_2, x_1) \cdot p - z = 0$ . The system of ODEs therefore reads in part

$$\dot{x}_1 = -x_2, \quad \dot{x}_2 = x_1,$$

which is the well know system solved by the sinusoidal functions. From the boundary  $(x_1, 0)$  we see that  $x_2 = 0$  when  $s = 0$ . Therefore  $x_2 = r \sin s$  and  $x_1 = r \cos s$  for a constant  $r$ . The ODE describing the values of  $u$  is  $\dot{z} = z$ , so  $u(x(s)) = e^s u(x(0)) = e^s u(r, 0) = e^s g(r)$ . Solving for the parameters  $r, s$  in terms of the point  $x$  gives

$$u(x) = e^{\arctan(x_2/x_1)} g(|x|).$$

- (c) This is quite similar to part (a), albeit with more variables. From  $F = (x_1, 2x_2, 1) \cdot p - 3z$  it follows that

$$x(s) = (x_{10}e^s, x_{20}e^{2s}, x_{30} + s) = (ae^s, be^{2s}, s).$$

Already we can determine the appropriate parameter values for any point:  $s = x_3$ ,  $a = x_1 e^{-x_3}$ , and  $b = x_2 e^{-2x_3}$ . The the equation for the values is  $z = z(0)e^{3s}$ , so

$$u(x) = e^{3s}u(a, b, 0) = e^{3x_3} g(x_1 e^{-x_3}, x_2 e^{-2x_3}).$$

- (d) This PDE,  $F = (z, 1) \cdot p - 1$  is a little different to the others, because of the  $z$  in the coefficients of  $p$ . This creates a linkage in the system of ODEs:

$$\dot{x}_1 = z, \quad \dot{x}_2 = 1, \quad \dot{z} = 1.$$

Fortunately, we can solve for  $z$  first this time quite easily:  $z(s) = s + z(0)$ . Then  $x(s) = (\frac{1}{2}s^2 + sz(0) + a, s + a)$ , using the fact that the initial boundary is  $(a, a)$ . Hence we can say that  $z(0) = u(x(0)) = u(a, a) = \frac{1}{2}a$  and  $a = x_2 - s$ , which allows us to solve for  $s$ :

$$\begin{aligned} x_1 &= \frac{1}{2}s^2 + s\frac{1}{2}(x_2 - s) + x_2 - s \\ x_1 - x_2 &= \frac{1}{2}x_2 s - s \\ s &= \frac{2x_1 - 2x_2}{x_2 - 2}. \end{aligned}$$

Finally, what we are interested in is the value of the solution  $u$  on these curves, and  $u(x(s)) = z(s) = s + z(0) = s + \frac{1}{2}(x_2 - s)$ , ie

$$u(x) = \frac{1}{2}x_2 + \frac{1}{2} \frac{2x_1 - 2x_2}{x_2 - 2}.$$

Solutions are due on Tuesday 12 noon, the day before the tutorial. Please email to [r.ogilvie@math.uni-mannheim.de](mailto:r.ogilvie@math.uni-mannheim.de). One possibility is to write your solutions neatly by hand and then scan them with your phone to make a pdf. There are many apps that do this; two examples on Android are ‘Tiny Scanner’ and ‘Simple Scanner’.

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