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Preparatory Exercises

15. Second order differential operators Let $a_{ij}, \tilde{a}_{ij}, b_i, \tilde{b}_i, c, \tilde{c}_i$, and \tilde{d} be real functions on the open set $\Omega \subset \mathbb{R}^n$. Any linear differential operator $L: C^2(\Omega) \to C(\Omega)$ of second order may be written as

$$(Lu)(x) = \sum_{i,j=1}^{n} a_{ij}(x)\partial_i\partial_j u(x) + \sum_{i=1}^{n} b_i(x)\partial_i u(x) + c(x)u(x).$$

$$(1)$$

This is called *general form* or *non-divergence form*. In contrast, we say that the operator is in *divergence form* when it is written as:

$$(Lu)(x) = \sum_{i=1}^{n} \left(\sum_{j=1}^{n} \partial_i (\tilde{a}_{ij}(x) \partial_j u(x)) + \partial_i (\tilde{b}_i(x) u(x)) + \tilde{c}_i(x) \partial_i u \right) + \tilde{d}(x) u(x).$$

- (a) Give the definition for a second order differential operator to be elliptic.
- (b) Assume further that all the coefficient functions are differentiable. Show that the two forms are equivalent. Give the relationship between the coefficient functions.
- (c) Define, for a constant symmetric matrix A, the second order differential operator L on \mathbb{R}^n .

$$(Lu)(x) := \nabla \cdot (A\nabla u(x))$$

Show that L is elliptic exactly when there is an invertible linear map $\varphi : \mathbb{R}^n \to \mathbb{R}^n$ such that $L(u \circ \varphi) = (\triangle u) \circ \varphi$.

[Hint. A can be diagonalised by orthogonal matrices.]

Now let $\widetilde{\Omega} \subset \mathbb{R}^n$ be another open set and $\varphi : \Omega \to \widetilde{\Omega}$ a C^2 -diffeomorphism. That is, φ is bijective, and both φ and φ^{-1} are twice continuously differentiable.

- (d) Show that $\widetilde{L}(\widetilde{u}) \circ \varphi = L(\widetilde{u} \circ \varphi)$ defines a second order differential operator \widetilde{L} on $\widetilde{\Omega}$ for $\widetilde{u} \in C^2(\widetilde{\Omega})$. You may do this by writing \widetilde{L} is general form.
- (e) Now suppose that Ω und $\widetilde{\Omega}$ are bounded and that both functions φ , φ^{-1} and their derivatives extend continuously to the closure $\overline{\Omega}$, $\overline{\widetilde{\Omega}}$ respectively. Under this hypothesis, show that \widetilde{L} is an elliptic operator exactly when L is. (Note, the relationship between L and \widetilde{L} is symmetric, so it suffices to prove one direction only.)

In Class Exercises

16. Neumann Problems.

In this question we consider the Neumann problem for the Laplace equation on the unit ball in \mathbb{R}^2 . [Note: One may freely use the Laplace-Operator in polar coordinates from Sheet 1.]

(a) Let $u \in C^2(\overline{B(0,1)})$ be a harmonic function on B(0,1), with the polar coordinate form $u = u(r,\varphi)$ (for $0 \le r \le 1$ and $0 < \varphi \le 2\pi$). Show that

$$\int_{\partial B(0,1)} \frac{\partial u}{\partial r}(x) d\sigma(x) = 0$$

holds.

- (b) Hence show that there is no solution to the Neumann problem $\Delta u = 0$ on B(0,1) with $\frac{\partial u}{\partial r} = \sin^2(\varphi)$ on $\partial B(0,1)$.
- (c) Find all solutions to $\triangle u = 0$ on B(0,1) with $\frac{\partial u}{\partial r} = \sin(\varphi)$ on $\partial B(0,1)$.

17. Compact Operators.

Let X, Y be Banach spaces. A linear, continuous mapping $T : X \to Y$ is called compact when for every bounded sequence $(x_m)_{m \in \mathbb{N}}$ in X there exists a subsequence $(x_{m_l})_{l \in \mathbb{N}}$ on which $(Tx_{m_l})_{l \in \mathbb{N}}$ converges.

- (a) Show that a linear continuous mapping $T: X \to Y$ is compact exactly when the image of the unit ball $B(0,1) = \{x \in X \mid ||x|| < 1\}$ of X is relatively compact. (Recall that relatively compact means that the closure $\overline{T[B(0,1)]}$ is compact.)
- (b) Let X be a Banach space and $id_X : X \to X$ be the identity mapping. Show that id_X is a compact operator if and only if X is finite-dimensional.

18. A detail from the proof of Schauder's fixed point theorem.

Optional: Let K and \tilde{K} be bounded, closed, convex subets of \mathbb{R}^n with non-empty interiors. Prove that K and \tilde{K} are homeomorphic.