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Query Optimization

Exercise sheet 2

Exercise 1

The following equivalences hold for 2-valued logic. In the context of database systems we have to deal with 3-valued logic (NULL values). Which of these equivalences holds for 3-valued logic? For the ones that don't hold, find a counter example. For the ones that hold, proof the equivalence by evaluating the truth table. Note that you only have to evaluate the cases where *unknown* occurs since you can assume that they hold for 2-valued logic.

Exercise 1 a)

 $\begin{array}{l} x \wedge \neg x = false \\ \text{and} \\ x \vee \neg x = true \end{array}$

Exercise 1 b)

 $(x \land y) \land z = x \land (y \land z)$ and $(x \lor y) \lor z = x \lor (y \lor z)$

Exercise 2

Greedy algorithms are applied to solve optimization problems. The solution obtained is not necessarily globally optimal. Greedy algorithms construct a solution step-by-step where each step is locally optimal. Steps taken cannot be undone in subsequent steps. Greedy algorithms terminate once a complete solution is found.

Exercise 2 a)

Using your favorite book on algorithms or Wikipedia, read about the greedy algorithm technique.

Exercise 2 b)

Implement either GreedyJoinOrdering-1 or GreedyJoinOrdering-2 from Chapter 3.2.1 Heuristics in the script.

Exercise 2 c)

What types of query graphs can GreedyJoinOrdering-1 and GreedyJoinOrder-2 handle? What type of join trees do they generate?

Exercise 3

You are given the cardinalities for relations $R_i, i \in \{1, ..., 4\}$ together with their join selectivities:

 $|R_1| = 10, |R_2| = 100, |R_3| = 1000, |R_4| = 25$ $f_{1,2} = 0, 1, f_{2,3} = 0, 2, f_{1,3} = 0, 4, f_{3,4} = 0, 1$

We already know that there is a large number of possible join trees (120, bushy and cross-products considered).

To see how costs vary from one join tree to another, compute the cost for some of the join trees for the cost functions C_{out} , C_{nlj} , C_{hj} and C_{smj} .

You will find their definitions in the script.

Note that the cost of a cross product $e_1 \times e_2$ is given by $|e_1| * |e_2|$.