

# Entropy versus diffusive PDEs

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# Partial Differential Equations and the Universe

“The book of Nature is written in mathematical language.”

Galileo Galilei, 1564-1642

Updated version:

“The book of Nature is (mostly) written in the language of **Partial Differential Equations.**”

Partial Differential Equations (PDEs) are widely used in the applied sciences to describe a lot of phenomena.

The analysis of PDEs is a very active and challenging field of Mathematics.

# Some classes of PDEs that have caught my attention

**Evolution equations:** describe how relevant physical quantities change with time (transient systems).

**Diffusion equations:** evolution mainly driven by tendency of particles to move in opposition to concentration gradients (“diffusion”).

**Reaction-diffusion systems:** important role played by “reaction terms”, arising from many different physical phenomena, like e.g. chemical reactions.

**Cross-diffusion:** diffusion of a species influenced by the density gradient of other species.

**Nonlocal diffusion:** diffusion effect at some point influenced by the values of concentration gradients in the whole spatial domain.

Of course, other types of PDEs exist (hyperbolic conservation laws, stationary elliptic problems ...)

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→ **Cross-diffusion:** diffusion of a species influenced by the density gradient of other species.

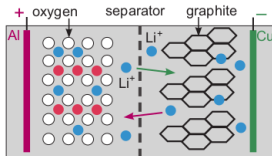
**Nonlocal diffusion:** diffusion effect at some point influenced by the values of concentration gradients in the whole spatial domain.

Today I will focus on (reaction-)cross-diffusion PDEs.

# Cross-diffusion PDEs in the applied sciences

Some examples of cross-diffusion PDEs from applied sciences:

- the Shigesada-Kawasaki-Teramoto (SKT) model in biology governs the interaction of two competing species in the same environment;
- the Maxwell-Stefan equations in gas dynamics describe diffusion in multicomponent fluids under the assumption of steady state;
- models for ion transport in fluid mixtures describing the time evolution of systems of electrically charged particles;
- models for tumor growth analyzing in a quantitative way the development of cancerous cells conglomerates.



# Cross-diffusion systems

Heat equation:

$$\partial_t u = \Delta u, \quad t > 0, \quad x \in \Omega \subset \mathbb{R}^d.$$

Reaction-diffusion system with **diagonal diffusion**: for  $i = 1, \dots, n$ ,

$$\partial_t u_i = \operatorname{div}(a_i(u_i) \nabla u_i) + f_i(u), \quad t > 0, \quad x \in \Omega \subset \mathbb{R}^d.$$

Reaction-cross-diffusion systems: for  $i = 1, \dots, n$ ,

$$\partial_t u_i = \sum_{j=1}^n \operatorname{div}(A_{ij}(u) \nabla u_j) + f_i(u), \quad t > 0, \quad x \in \Omega \subset \mathbb{R}^d,$$

where  $u = (u_1, \dots, u_n) : \Omega \times (0, \infty) \rightarrow \mathbb{R}^n$  is the unknown of the system (typically a vector of densities or concentrations of species),  $A = A(u) \in \mathbb{R}^{n \times n}$  is the diffusion matrix, and  $f = f(u) \in \mathbb{R}^n$  is the reaction term.

Reaction-cross-diffusion systems (compact notation):

$$\partial_t u = \operatorname{div} (A(u) \nabla u) + f(u), \quad t > 0, \quad x \in \Omega \subset \mathbb{R}^d, \quad (1)$$

where  $u = (u_1, \dots, u_n) : \Omega \times (0, \infty) \rightarrow \mathbb{R}^n$  is the unknown of the system (typically a vector of densities or concentrations of species),  $A = A(u) \in \mathbb{R}^{n \times n}$  is the diffusion matrix, and  $f = f(u) \in \mathbb{R}^n$  is the reaction term.

Some interesting analytical questions:

- existence of solutions (global in time, weak solutions);
- uniform boundedness, nonnegativity, other algebraic constraints;
- the long-time behaviour of solutions (convergence to steady state);
- uniqueness of solutions.

# Mathematical challenges of cross-diffusion

The analytical study of cross-diffusion PDEs is **challenging!**

Cross-diffusion  $\Rightarrow$  strong coupling between the equations.

Diffusion matrix  $A(u)$  in general not positive (semi)definite  
 $\Rightarrow$  standard coercivity-based approaches ineffective (straightforward monotonicity properties not available).

No general maximum/minimum principle  $\Rightarrow$  showing upper/lower bounds for the solution of the system is often a very difficult problem.



# The “entropy method”

[Burger-Di Francesco-Pietschmann-Schlake '10, Jüngel '15, Jüngel '16].

If a convex functional  $\mathcal{H} = \mathcal{H}[u]$  exists (usually termed **mathematical entropy**) such that (1) can be (formally) restated as

$$\partial_t u = \operatorname{div}(B \nabla \mathcal{H}'[u]) + f(u), \quad t > 0, \quad x \in \Omega \subset \mathbb{R}^d, \quad (2)$$

with  $\mathcal{H}'$  Fréchet derivative of  $\mathcal{H}$  and  $B$  a **positive semi-definite** matrix, then we say that (1) possesses an **entropy structure**.

$$\mathcal{H}[u] = \int_{\Omega} h(u) dx \quad \Rightarrow \quad \mathcal{H}'[u] = h'(u) \equiv w \text{ **entropy variable** .}$$

Example (heat equation):

$$\partial_t u = \operatorname{div}(u \nabla \log u), \quad \log u = \mathcal{H}'[u], \quad \mathcal{H}[u] = \int_{\Omega} (u \log u - u) dx.$$

# The “entropy method”, 2

If (1) admits an entropy structure (and  $f \equiv 0$ ) then

$$\frac{d}{dt} \mathcal{H}[u] = - \sum_{i=1}^n \int_{\Omega} \partial_{x_i} w \cdot B(w) \partial_{x_i} w \, dx \leq 0,$$

i.e.  $\mathcal{H}$  is nonincreasing along the (smooth) solutions to (1).

- It can be generalized to the case  $f \neq 0$  with suitable additional assumptions on  $f$ .
- Suitable lower bounds for  $-\frac{d}{dt} \mathcal{H}[u] \Rightarrow$  crucial a-priori estimates for the solution  $u$  to (1).

Example (heat equation):

$$\frac{d}{dt} \mathcal{H}[u] = - \int_{\Omega} u |\nabla \log u|^2 \, dx, \quad \mathcal{H}[u] = \int_{\Omega} (u \log u - u) \, dx.$$

# The “entropy method”, 3

If  $h' : \mathcal{D} \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$  is globally invertible:

$$u = u(w) = (h')^{-1}(w) \quad \Rightarrow \quad u \in \mathcal{D} \quad \text{on } \{|w| < \infty\}.$$

$\Rightarrow$  If  $\mathcal{D}$  is bounded and  $w$  is a.e. finite, then  $u$  is bounded with bounds that only depend on  $\mathcal{D}$ .

Example: “Fermi-Dirac” entropy:

$$\mathcal{H}[u] = \int_{\Omega} (u \log u + (1 - u) \log(1 - u)) dx.$$

$$w = \mathcal{H}'[u] = \log \frac{u}{1 - u} \quad \Rightarrow \quad u = \frac{e^w}{1 + e^w} \in \mathcal{D} \equiv (0, 1).$$

**Three steps** in existence argument.

- 1 Formulation of an approximated problem. Time semi-discretization + regularization. Obtain family  $(u^{(\tau)})_{\tau>0}$  of approximated solutions.
- 2 Entropy inequality for approximated problem  $\Rightarrow$  estimates for  $u^{(\tau)}$  in Sobolev spaces.
- 3 Aubin-Lions, Div-Curl lemma  $\Rightarrow$  compactness for  $u^{(\tau)} \Rightarrow u^{(\tau)} \rightarrow u$  as  $\tau \rightarrow 0$ , and  $u$  is solution to original PDEs.

Sometimes the bounds for  $u^{(\tau)}$  are not sufficient to get compactness. The bounds might become ineffective when  $u^{(\tau)}$  approaches some critical value or set  $\rightarrow$  **Degeneracy**.

Possible solution to degeneracy: **generalize** Aubin-Lions Lemma to degenerate case. Example: [NZ-Jüngel, Ann. Inst. H. Poinc. (C) 2017].

# About long-time behaviour

**Idea:** the solution  $u(t)$  should converge to some “steady state”  $u^\infty$  in some norm. Use *relative entropy*  $\mathcal{H}[u(t)|u^\infty]$  to measure distance between solution and steady state.

**Key tool:** relative entropy inequality

$$\frac{d}{dt} \mathcal{H}^{rel}[u|u^\infty] + I[u, \nabla u] \leq 0.$$

**Crucial point:** relate the entropy dissipation  $I[u, \nabla u]$  and the entropy  $\mathcal{H}^{rel}[u|u^\infty]$  (remember Fokker-Planck).

Gronwall's lemma  $\Rightarrow$  upper bound for  $\mathcal{H}[u(t)|u^\infty]$  which decays in time.  
 $\Rightarrow u(t) \rightarrow u^\infty$  in some norm.

Much more difficult for (cross-diffusion) systems than in the scalar case.  
No log-Sobolev inequality for systems!

**Result:** in [NZ-Jüngel, Ann. Inst. H. Poinc. (C) 2017] we proved **algebraic** convergence to the steady state for **degenerate** cross-diffusion system.

[Gajewsky 1994]: take two solutions  $u, v$  with the same initial datum and consider the “relative entropy”  $H^{rel}[u, v]$  between them:

$$H^{rel}[u, v] = H[u] + H[v] - 2H\left[\frac{u+v}{2}\right].$$

- ▶  $H$  convex  $\Rightarrow H^{rel}[u, v] \geq 0$  and  $H^{rel}[u, v] = 0$  if and only if  $u = v$ .
- ▶  $H^{rel}[u, v]|_{t=0} = 0$  since  $u = v$  at initial time.
- ▶ So, if one can prove that  $\frac{d}{dt} H^{rel}[u(t), v(t)] \leq 0$  for  $t > 0$ , it follows that  $u(t) = v(t)$  for  $t > 0$ .

**Very difficult** for cross-diffusion systems!

**Idea:** argument can be applied to “partially decoupled” systems together with  $H^{-1}$  method [NZ-Jüngel, Ann. Inst. H. Poinc. (C) 2017].

# A particular cross-diffusion PDEs system

A class of multi-species population models with degenerate cross-diffusion [NZ-Jüngel, Ann. Inst. H. Poinc. (C) 2017]:

$$\partial_t u_i = \sum_{j=1}^n \operatorname{div} (A_{ij}(u) \nabla u_j) \quad \text{in } \Omega \times (0, T), \quad i = 1, \dots, n,$$

$$A_{ij}(u) = q(u_{n+1})^2 \frac{\partial}{\partial u_j} \left( \frac{u_i p_i(u)}{q(u_{n+1})} \right), \quad i, j = 1, \dots, n,$$

where

$u = (u_1, \dots, u_n) : \Omega \times (0, T) \rightarrow \mathbb{R}^n$  proportions of subpopulations,

$u_{n+1} = 1 - \sum_{i=1}^n u_i =$  proportion of unoccupied space.

Constraints:  $u_i \geq 0$ ,  $i = 1, \dots, n$ , and  $u_{n+1} \geq 0$  if  $q(u_{n+1}) \neq 1$ .

Employed to model spatial segregation of interacting populations, motility of biological cells, ion transport through nanopores.

# The analytical problem

**Goal:** study existence, uniqueness and long-time behaviour of solutions to the initial-boundary value problem:

find  $u : \Omega \times (0, T) \rightarrow D = \{u \in (0, 1)^n : \sum_{i=1}^n u_i < 1\}$  such that:

$$\partial_t u = \operatorname{div}(A(u)\nabla u) \quad \text{in } \Omega \times (0, T), \quad (\text{PB.1})$$

$$\partial_\nu u = 0 \quad \text{on } \partial\Omega \times (0, T), \quad (\text{PB.2})$$

$$u(\cdot, 0) = u^0 \quad \text{on } \Omega, \quad (\text{PB.3})$$

with  $A(u)$  given by:

$$A_{ij}(u) = q(u_{n+1})^2 \frac{\partial}{\partial u_j} \left( \frac{u_i p_i(u)}{q(u_{n+1})} \right), \quad u_{n+1} = 1 - \sum_{i=1}^n u_i.$$

Entropy structure with entropy functional:  $\mathcal{H}[u] = \int_{\Omega} h(u) dx,$

$$h(u) = \sum_{i=1}^n (u_i \log u_i - u_i + 1) + \int_a^{u_{n+1}} \log q(s) ds + \chi(u) \quad u \in \mathcal{D}.$$

**Hypothesis:**  $q(0) = 0$  (+ other technical assumptions).



# Existence of bounded weak solutions

We proved global-in-time existence of **uniformly bounded** weak solutions  $u : \Omega \times (0, T) \rightarrow \overline{\mathcal{D}}$  such that  $\mathcal{H}[u(t_2)] \leq \mathcal{H}[u(t_1)]$  for  $t_1 \leq t_2$ .

**Key point:** a-priori estimates for approximate solution  $u^{(\tau)}$ :

$$\sum_{i=1}^n \|q(u_{n+1}^{(\tau)})^{1/2} \nabla(u_i^{(\tau)})^{1/2}\|_{L^2(\Omega)}^2 + \|\nabla q(u_{n+1}^{(\tau)})^{1/2}\|_{L^2(\Omega)}^2 \leq C.$$

$q(0) = 0$ : **Degeneracy!** Compactness?

**Novel idea:** generalize Aubin-Lions lemma to the degenerate case.

- ▶ Bounds for  $\nabla q(u_{n+1}^{(\tau)})^{1/2}$  and  $\partial_t u_{n+1}^{(\tau)} \Rightarrow$  compactness for  $u_{n+1}^{(\tau)}$ .
- ▶ Strong convergence for  $u_{n+1}^{(\tau)}$   
+ Bounds for  $q(u_{n+1}^{(\tau)})^{1/2} \nabla(u_i^{(\tau)})^{1/2}$  and  $\partial_t u_i^{(\tau)}$   
 $\Rightarrow$  compactness for  $q(u_{n+1}^{(\tau)})^{1/2} f(u^{(\tau)})$  for every  $f$  continuous.

This is enough to pass to the limit  $\tau \rightarrow 0$  in the approximate equations.

# Long-time behaviour of solutions

**Constant Dirichlet boundary conditions**  $u = u_D$ .

$\Rightarrow u \rightarrow u^\infty \equiv u_D$  in  $L^1(\Omega)$  with **algebraic rate**:

$$\|u(t) - u^\infty\|_{L^1(\Omega)} \leq \frac{C}{\sqrt{1+t}} \quad \forall t > 0.$$

**Key idea:** relative entropy inequality:

$$\frac{d}{dt} \mathcal{H}[u(t)|u^\infty] \leq - \int_{\Omega} \sum_{i=1}^{n+1} |\nabla \Phi_i(u)|^2 dx$$

$$\text{(Poincaré)} \leq -c_P \int_{\Omega} \sum_{i=1}^{n+1} |\Phi_i(u) - \Phi_i(u^\infty)|^2 dx$$

$$\text{(Computations)} \leq -c \mathcal{H}[u(t)|u^\infty]^2$$

**Algebraic** decay rate from Gronwall argument.

# Uniqueness of solutions

Uniqueness of **weak** solutions. No higher regularity assumptions!

Assume that  $p_i(u) \equiv 1$ ,  $i = 1, \dots, n$ . Then the weak solution  $u$  with the properties stated in the existence theorem is unique.

Equations become:

$$\partial_t u_i - \operatorname{div}(q(u_{n+1}) \nabla u_i - u_i \nabla q(u_{n+1})) = 0 \quad (i = 1, \dots, n).$$

“Partially decoupled equations”: summing equations in  $i$  yields equation for  $u_{n+1}$  **alone**. Two steps:

1. Prove uniqueness for  $u_{n+1}$  ( $H^{-1}$  method).
2. Prove uniqueness for  $u_i$ ,  $i = 1, \dots, n$  (relative entropy).

Gajewsky method with “relative entropy between to solutions  $u, v$ ”:

$$\Xi = S[u] + S[v] - 2S\left[\frac{u+v}{2}\right], \quad S[u] = \sum_{i=1}^n \int_{\Omega} u_i \log u_i dx.$$

Convexity of the Fisher information functional  $\Rightarrow \Xi(t)$  nonincreasing.

## Summary.

- We explained a method, based on the idea of mathematical entropy, employed for the analysis of nonlinear PDEs systems.
- We adapted the method to a multi-species population model with degenerate cross-diffusion.
- **Key original ideas:**
  - ▶ generalized Aubin-Lions Lemma to cope with degeneracy;
  - ▶ algebraic decay rate to steady state for degenerate cross-diffusion system;
  - ▶ uniqueness for “partially decoupled” cross-diffusion PDEs.

## Outlook.

- Strongly degenerate PDEs systems. Example: model for gang dynamics in a city (coop. with A. Barbaro, N. Rodriguez).
- Hölder regularity for cross-diffusion systems via Campanato iteration employing entropy functional (coop. with C. Raithel, M. Braukhoff).
- Apply entropy method to nonlocal diffusion PDEs systems (coop. with M. Gualdani).

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